**Team 10 Member Contributions**

* **Gus \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_**
  + Final design of robot
  + Initial line follow logic and implementation of RedMode
  + Stack logic and implementation
  + Overseeing periodic testing of robot
  + Commenting final draft of MazeSolver
  + Configured git repository
  + Organized and assigned group work
* **Sam \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_**
  + Initial and second designs of robot
  + Implementation of HSV for line following
  + Fine tuning of HSV code
  + Stack logic
  + Color sensor calibration method
  + Check nonsensical HSV numbers repeatedly because they always change
* **Melody\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_**
  + Fine tuning line following with RedMode
  + Implementation and fine tuning of touch sensor
  + Merging touch sensor and line follow code
  + Logic for sensing blue squares at intersections
  + Foil behavior
  + Team and robot names
    - Also correcting Gus’s spelling
* **Binrong\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_**
  + Helped test line following with RedMode
  + Strategy for getting back to the line