**Team 10 Member Contributions**

* **Gus Gamble \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_**
  + Final design of robot
  + Initial line follow logic and implementation of RedMode
  + Stack logic and implementation
  + Overseeing periodic testing of robot
  + Commenting final draft of MazeSolver
  + Configured git repository
  + Organized and assigned group work
* **Sam Frey \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_**
  + Initial and second designs of robot
  + Implementation of HSV for line following
  + Fine tuning of HSV code
  + Stack logic
  + Color sensor calibration method
* **Melody Lee \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_**
  + Fine tuning line following with RedMode
  + Implementation and fine tuning of touch sensor
  + Merging touch sensor and line follow code
  + Logic for sensing blue squares at intersections
  + Team and robot names
* **Binrong Fu \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_**
  + Helped test line following with RedMode
  + Strategy for getting back to the line